

IN THE SPECIFICATION

Please amend the Abstract on page 24 as follows:

~~This invention provides~~ In a vehicle operation control method and vehicle operation control apparatus ~~which protects a vehicle driver from a feeling of disharmony in his steering operation. In vehicle operation control processing, a change amount $\Delta\theta_h$ in steering angle θ_h by a steering wheel is detected by means of a steering angle change amount detecting means 40a1, a variable gain G is controlled based on a vehicle velocity V by a variable gain multiplying means 40a2 and the~~ then, that controlled variable gain G is multiplied with the change amount $\Delta\theta_h$ in the steering angle. Then, that multiplication result is integrated ~~by an integrating means 40a3~~ and the integration result is converted to an object actual steering angle ~~by an object actual steering angle computing means 40a4. A deflection amount detecting means 40a5 obtains a deflection between the actual steering angle θ_T and the object actual steering angle θ_T^* so as is used~~ to compute an angle deflection $\Delta\theta_T$. ~~Thus, when the steering wheel is maintained, the change amount $\Delta\theta_h$ in the steering angle θ_h becomes zero and a result of multiplication with the variable gain G also becomes zero, so that no changes occurs in a result of integration of the multiplication results. Therefore, no changes occur in the actual steering angle of the driven wheels, thereby protecting the vehicle driver from a feeling of disharmony in his steering operation.~~